

# Chapter 5

## Scalar product and orthogonality

### 5.1 Scalar product

Recall that the notion of a vector space has been introduced as an abstract version of the properties shared both by  $\mathbb{R}^n$  and by  $M_{mn}(\mathbb{R})$ . Similarly, we have introduced the scalar product on  $\mathbb{R}^n$  already in Chapter 1, let us now consider an abstract version of it. For simplicity, we introduce it on real vector spaces, but a slightly more general version will be considered once the complex numbers will be at our disposal.

**Definition 5.1.1.** A scalar product on a real vector space  $V$  is a map  $\langle \cdot, \cdot \rangle : V \times V \rightarrow \mathbb{R}$  such that for any  $X, Y, Z \in V$  and  $\lambda \in \mathbb{R}$  one has

$$(i) \quad \langle X, Y \rangle = \langle Y, X \rangle,$$

$$(ii) \quad \langle X + Y, Z \rangle = \langle X, Z \rangle + \langle Y, Z \rangle,$$

$$(iii) \quad \langle \lambda X, Y \rangle = \lambda \langle X, Y \rangle,$$

$$(iv) \quad \langle X, X \rangle \geq 0 \text{ and } \langle X, X \rangle = 0 \text{ if and only if } X = \mathbf{0}.$$

**Example 5.1.2.** For  $V = \mathbb{R}^n$  and  $X, Y \in V$  one sets  $\langle X, Y \rangle := X \cdot Y$  and one can check that the four conditions above are satisfied.

**Example 5.1.3.** For  $a, b \in \mathbb{R}$  with  $a < b$  one considers  $V = C([a, b]; \mathbb{R})$  and for any  $f, g \in V$  one defines

$$\langle f, g \rangle := \int_a^b f(x)g(x)dx.$$

It is easily checked that this defines a scalar product on  $V$ , see Exercise 5.5. For information, this scalar product extends to the set of  $L^2$ -functions (the set of square integrable functions).

**Definition 5.1.4.** If  $V$  is a real vector space endowed with a scalar product, one says that  $X, Y \in V$  are orthogonal if  $\langle X, Y \rangle = 0$ , and one writes  $X \perp Y$ . If  $S$  is a subset of  $V$ , one writes

$$S^\perp := \{Y \in V \mid \langle X, Y \rangle = 0 \text{ for all } X \in S\}$$

and call it the orthogonal subspace of  $S$ .

One easily shows that  $S^\perp$  is always a subspace of  $V$ .

**Definition 5.1.5.** For any real vector space  $V$  endowed with a scalar product and for any  $X \in V$  we set

$$\|X\| := \sqrt{\langle X, X \rangle}$$

and call it the norm of  $X$  (associated with the scalar product  $\langle \cdot, \cdot \rangle$ ).

**Lemma 5.1.6.** For any real vector space  $V$  endowed with a scalar product, for any  $X, Y \in V$  and for  $\lambda \in \mathbb{R}$  one has

- (i)  $\|\lambda X\| = |\lambda| \|X\|$ ,
- (ii)  $\|X + Y\|^2 = \|X\|^2 + \|Y\|^2$  if and only if  $X \perp Y$  (Pythagoras theorem)
- (iii)  $\|X + Y\|^2 + \|X - Y\|^2 = 2\|X\|^2 + 2\|Y\|^2$ ,
- (iv)  $\|X + Y\| \leq \|X\| + \|Y\|$ .

The proof will be provided in Exercise 5.1. The following statement is a generalization of a property already derived in the context of  $\mathbb{R}^n$ .

**Lemma 5.1.7.** For any real vector space  $V$  endowed with a scalar product and for any  $X, Y \in V$  one has

$$|\langle X, Y \rangle| \leq \|X\| \|Y\|. \quad (5.1.1)$$

*Proof.* Let us first consider the trivial case  $Y = \mathbf{0}$  for which (5.1.1) is an equality with 0 on both sides.

Now, assume that  $Y \neq \mathbf{0}$  and set  $c := \frac{\langle X, Y \rangle}{\|Y\|^2}$ . Then let us observe that  $(X - cY) \perp Y$ , since

$$\langle X - cY, Y \rangle = \langle X, Y \rangle - \frac{\langle X, Y \rangle}{\|Y\|^2} \langle Y, Y \rangle = 0.$$

It follows by Pythagoras theorem that

$$\|X\|^2 = \|(X - cY) + cY\|^2 = \|X - cY\|^2 + \|cY\|^2 = \|X - cY\|^2 + c^2\|Y\|^2,$$

which implies that  $\|X\|^2 \geq c^2\|Y\|^2$ , or equivalently  $\|X\| \geq |c| \|Y\|$ . Note that this inequality can also be rewritten as  $|c| \leq \frac{\|X\|}{\|Y\|}$ .

By collecting these information one gets

$$|\langle X, Y \rangle| = |c| \|Y\|^2 \leq \frac{\|X\|}{\|Y\|} \|Y\|^2 = \|X\| \|Y\|,$$

which corresponds to the claim. □

## 5.2 Orthogonal bases

**Definition 5.2.1.** Let  $V$  be a real vector space endowed with a scalar product, and let  $\{V_1, \dots, V_n\}$  be a basis for  $V$ . The basis is called *orthogonal* if  $\langle V_i, V_j \rangle = 0$  whenever  $i, j \in \{1, \dots, n\}$  and  $i \neq j$ . If in addition  $\langle V_i, V_i \rangle = 1$  for any  $i \in \{1, \dots, n\}$  the basis is called *orthonormal*.

**Example 5.2.2.** The standard basis  $\{E_1, \dots, E_n\}$  of  $\mathbb{R}^n$  is an orthonormal basis.

The following result is of conceptual importance, and rather well-known.

**Theorem 5.2.3** (Graham-Schmidt). Let  $V$  be a real vector space of dimension  $n$  endowed with a scalar product. Then there exists an orthonormal basis for  $V$ .

The proof consists in the explicit construction of an orthonormal basis.

*Proof.* Let  $\{V_1, \dots, V_n\}$  be an arbitrary basis for  $V$  (such a basis exists since otherwise the dimension of  $V$  would not be defined), and let us set

$$\begin{aligned} V'_1 &:= \frac{1}{\|V_1\|} V_1 \\ V'_2 &:= \frac{1}{\|V_2 - \langle V_2, V'_1 \rangle V'_1\|} (V_2 - \langle V_2, V'_1 \rangle V'_1) \\ &\vdots \\ V'_n &:= \frac{1}{\|V_n - \sum_{i=1}^{n-1} \langle V_n, V'_i \rangle V'_i\|} \left( V_n - \sum_{i=1}^{n-1} \langle V_n, V'_i \rangle V'_i \right), \end{aligned}$$

where the prefactors are chosen such that  $\|V'_j\| = 1$  (note that  $V_j - \sum_{i=1}^{j-1} \langle V_j, V'_i \rangle V'_i$  is always different from  $\mathbf{0}$  since otherwise  $V_j$  would be a linear combination of  $V_1, \dots, V_{j-1}$  which is not possible by assumption). Then, it simply remains to observe that  $V'_j \perp V'_k$  for any  $j \neq k$ . As a consequence, the elements  $V'_j$  generate an orthonormal basis for  $V$ , as expected.  $\square$

## 5.3 Bilinear maps

The notion of bilinear maps will be useful for calculus II.

**Definition 5.3.1.** Let  $V, W, U$  be vector spaces over the same field  $\mathbb{F}$ . A map  $T : V \times W \rightarrow U$  is *bilinear* if it is linear in each argument, namely for any  $X, X_1, X_2 \in V$ , any  $Y, Y_1, Y_2 \in W$  and  $\lambda \in \mathbb{F}$  one has

$$(i) \quad T(X_1 + X_2, Y) = T(X_1, Y) + T(X_2, Y),$$

$$(ii) \quad T(\lambda X, Y) = \lambda T(X, Y),$$

$$(iii) \quad T(X, Y_1 + Y_2) = T(X, Y_1) + T(X, Y_2),$$

$$(iv) \quad T(X, \lambda Y) = \lambda T(X, Y).$$

**Example 5.3.2.** The scalar product  $\langle \cdot, \cdot \rangle : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$  is a bilinear map on the Euclidean space  $\mathbb{R}^n$ .

**Example 5.3.3.** If  $\mathcal{A} \in M_{mn}(\mathbb{F})$  one can define a bilinear map  $F_{\mathcal{A}} : \mathbb{F}^m \times \mathbb{F}^n \rightarrow \mathbb{F}$  for any  $X \in \mathbb{F}^m$  and  $Y \in \mathbb{F}^n$  by

$$F_{\mathcal{A}}(X, Y) = {}^t X \mathcal{A} Y \equiv \underbrace{{}^t X}_{\in M_{1m}(\mathbb{F})} \underbrace{\mathcal{A}}_{\in M_{mn}(\mathbb{F})} \underbrace{Y}_{\in M_{n1}(\mathbb{F})} \in \mathbb{F}. \quad (5.3.1)$$

Note that it is easily checked that  $F_{\mathcal{A}}$  is indeed a bilinear map. For example, if  $\mathcal{A} = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$ ,  $X = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$  and  $Y = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ , then

$$F_{\mathcal{A}}(X, Y) = (1 \ 0) \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = (1 \ 0) \begin{pmatrix} 2 \\ 4 \end{pmatrix} = 2.$$

More generally, observe that if  $\mathcal{A} = (a_{ij})$ ,  $X = {}^t(x_1, \dots, x_m)$  and  $Y = {}^t(y_1, \dots, y_n)$  then

$${}^t X \mathcal{A} Y = X \cdot (\mathcal{A} Y) = \sum_{i=1}^m x_i (\mathcal{A} Y)_i = \sum_{i=1}^m x_i \sum_{j=1}^n a_{ij} y_j = \sum_{i=1}^m \sum_{j=1}^n a_{ij} x_i y_j.$$

We shall now see that many bilinear maps are of the form presented in the previous example. For that purpose, recall from Section 4.5 that if  $\mathcal{V} = \{V_1, \dots, V_m\}$  is a basis for a vector space  $V$  over  $\mathbb{F}$  and if  $\mathcal{X} \in V$  then the coordinate vector of  $\mathcal{X}$  is the element  $X = {}^t(x_1, \dots, x_m) \in \mathbb{F}^m$  such that  $\mathcal{X} = x_1 V_1 + \dots + x_m V_m$ . One has already introduced the notation  $(\mathcal{X})_{\mathcal{V}} = X$ . Similarly, for a basis  $\mathcal{W} = \{W_1, \dots, W_n\}$  of a vector space  $W$  over  $\mathbb{F}$  and for any  $\mathcal{Y} \in W$  one sets  $(\mathcal{Y})_{\mathcal{W}} = Y = {}^t(y_1, \dots, y_n) \in \mathbb{F}^n$  for its coordinate vector.

**Lemma 5.3.4.** Let  $V, W$  be vector spaces over a field  $\mathbb{F}$  and let  $F : V \times W \rightarrow \mathbb{F}$  be a bilinear map. If  $\mathcal{V} = \{V_1, \dots, V_m\}$  is a basis for  $V$ , and if  $\mathcal{W} = \{W_1, \dots, W_n\}$  is a basis for  $W$  then there exists  $\mathcal{A} \in M_{mn}(\mathbb{F})$  such that

$$F(\mathcal{X}, \mathcal{Y}) = {}^t X \mathcal{A} Y$$

for any  $\mathcal{X} \in V$ , any  $\mathcal{Y} \in W$  and with  $X = (\mathcal{X})_{\mathcal{V}}$  and  $Y = (\mathcal{Y})_{\mathcal{W}}$ .

*Proof.* By taking the bilinearity of  $F$  into account, one has

$$F(\mathcal{X}, \mathcal{Y}) = F\left(\sum_{i=1}^m x_i V_i, \sum_{j=1}^n y_j W_j\right) = \sum_{i=1}^m \sum_{j=1}^n x_i y_j F(V_i, W_j).$$

Thus, by setting  $a_{ij} = F(V_i, W_j) \in \mathbb{F}$  one deduces that

$$F(\mathcal{X}, \mathcal{Y}) = \sum_{i=1}^m \sum_{j=1}^n a_{ij} x_i y_j = {}^t X \mathcal{A} Y$$

with  $\mathcal{A} = (a_{ij})$ . □

**Remark 5.3.5.** *If  $V, W, U$  are vector spaces over the same field  $\mathbb{F}$  and if  $F_i : V \times W \rightarrow U$  are bilinear maps for  $i = 1, 2$ , then  $F_1 + F_2 : V \times W \rightarrow U$  is a bilinear map, and  $\lambda F_i$  is also a bilinear map. Thus, the set of bilinear maps from  $V \times W$  to  $U$  is a vector space.*

Let us end this section with two questions:

**Question:** Let  $V = W = \mathbb{R}^n$  and consider the map  $F$  defined by the usual scalar product

$$F(X, Y) = X \cdot Y \quad \text{for any } X, Y \in \mathbb{R}^n.$$

In view of Lemma 5.3.4, what is the matrix associated with this bilinear map with respect to the canonical basis of  $\mathbb{R}^n$  ?

**Question:** How does a bilinear map change when one performs a change of bases for the vector spaces  $V$  and  $W$  ?

## 5.4 Exercises

**Exercise 5.1.** Let  $V$  be a real vector space endowed with a scalar product. Prove the following relations for  $X, Y \in V$  and  $\lambda \in \mathbb{R}$ :

- (i)  $\|\lambda X\| = |\lambda| \|X\|$ ,
- (ii)  $\|X + Y\|^2 = \|X\|^2 + \|Y\|^2$  if and only if  $X \perp Y$ ,
- (iii)  $\|X + Y\|^2 + \|X - Y\|^2 = 2\|X\|^2 + 2\|Y\|^2$ ,
- (iv)  $\|X + Y\| \leq \|X\| + \|Y\|$ .

**Exercise 5.2.** Let  $\mathcal{A} = (a_{jk}) \in M_n(\mathbb{R})$  and define  $\text{Tr}(\mathcal{A}) = \sum_{j=1}^n a_{jj}$ , where  $\text{Tr}(\mathcal{A})$  is called the trace of  $\mathcal{A}$ . Show the following properties:

- (i)  $\text{Tr} : M_n(\mathbb{R}) \rightarrow \mathbb{R}$  is a linear map,
- (ii)  $\text{Tr}(\mathcal{A}\mathcal{B}) = \text{Tr}(\mathcal{B}\mathcal{A})$ , for any  $\mathcal{A}, \mathcal{B} \in M_n(\mathbb{R})$ ,
- (iii) If  $\mathcal{C} \in M_n(\mathbb{R})$  is an invertible matrix, then  $\text{Tr}(\mathcal{C}^{-1}\mathcal{A}\mathcal{C}) = \text{Tr}(\mathcal{A})$ ,
- (iv) If  $M_n^s(\mathbb{R})$  denotes the vector space of all  $n \times n$  symmetric matrices, then the map

$$M_n^s(\mathbb{R}) \times M_n^s(\mathbb{R}) \ni (\mathcal{A}, \mathcal{B}) \mapsto \text{Tr}(\mathcal{A}\mathcal{B}) \in \mathbb{R}$$

defines a scalar product on  $M_n^s(\mathbb{R})$ . We recall that a matrix  $\mathcal{A}$  is symmetric if  $\mathcal{A} = {}^t\mathcal{A}$ .

**Exercise 5.3.** Find an orthonormal basis for the subspace of  $\mathbb{R}^4$  defined by the three vectors  $\begin{pmatrix} 1 \\ 1 \\ 0 \\ 1 \end{pmatrix}$ ,  $\begin{pmatrix} 1 \\ 0 \\ -1 \\ 2 \end{pmatrix}$  and  $\begin{pmatrix} 1 \\ -2 \\ 0 \\ 0 \end{pmatrix}$ .

**Exercise 5.4.** Find an orthonormal basis for the space of solutions of the following systems:

$$\begin{aligned} \text{a) } & \begin{cases} 2x + y - z = 0 \\ 2x + y + z = 0 \end{cases} & \text{b) } & \{x - y + z = 0\} & \text{c) } & \begin{cases} 4x + 7y - \pi z = 0 \\ 2x - y + z = 0 \end{cases} \\ \text{d) } & \begin{cases} x + y + z = 0 \\ x - y = 0 \\ y + z = 0 \end{cases} \end{aligned}$$

**Exercise 5.5.** We consider the real vector space  $V := C([0, 1])$  made of continuous real functions on  $[0, 1]$  and endow it with the map

$$V \times V \ni (f, g) \mapsto \langle f, g \rangle := \int_0^1 f(x)g(x) dx \in \mathbb{R}.$$

Show that

- (i)  $\langle \cdot, \cdot \rangle$  is a scalar product on  $V$ ,
- (ii) If  $W$  is the subspace of  $V$  generated by the three functions  $x \mapsto 1$  (constant function),  $x \mapsto x$  (identity function), and  $x \mapsto x^2$ , find an orthonormal basis for  $W$ .

**Exercise 5.6.** For any symmetric matrix  $\mathcal{A} = (a_{ij}) \in M_n(\mathbb{R})$ , we define the map

$$F_{\mathcal{A}} : \mathbb{R}^n \times \mathbb{R}^n \ni (X, Y) \mapsto F_{\mathcal{A}}(X, Y) := {}^t X \mathcal{A} Y \in \mathbb{R}.$$

- (i) Show that  $F_{\mathcal{A}}$  is a bilinear map,
- (ii) Show that  $F_{\mathcal{A}}(X, Y) = F_{\mathcal{A}}(Y, X)$  for any  $X, Y \in \mathbb{R}^n$ .
- (iii) When does  $F_{\mathcal{A}}$  define a scalar product ?
- (iv) If  $\mathcal{A}$  is one of the following matrices, does  $F_{\mathcal{A}}$  define a scalar product ?

$$\mathcal{A} = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}, \quad \mathcal{A} = \begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{pmatrix}.$$

