

Reminder IX

• Wiener integral: if $f \in L^2([0, T])$, then

$Y_t := \int_0^t f(u) dB_u$ defines a Gaussian process $Y = (Y_t)_{t \in [0, T]}$.

• For $X \in M^2_{loc}([0, T])$, $Y_t := \int_0^t X_u dB_u$,

$Y = (Y_t)_{t \in [0, T]}$ has finite quadratic variation,
↑ and is continuous + infinite variation in general.

• Itô's lemma: $f \in C^2(\mathbb{R}^2)$, then

$$\bullet f(t, B_t) = f(0, 0) + \int_0^t [D_x f](s, B_s) dB_s + \int_0^t \left\{ [D_t f](s, B_s) + \frac{1}{2} [D_x^2 f](s, B_s) \right\} ds$$

• N-dimensional analog: ↗ only in terms of B... too restrictive!

$$f(t, B_t) = f(0, 0) + \int_0^t [\nabla f]^T(s, B_s) dB_s + \int_0^t \left\{ [D_t f](s, B_s) + \frac{1}{2} [\Delta f](s, B_s) \right\} ds$$

• Itô processes: $V \in M^2_{loc}([0, T])$, $D \in M^1_{loc}([0, T])$,

adapted to B , Set $X_t := X_0 + \int_0^t V_s dB_s + \int_0^t D_s ds$.

Then $X = (X_t)_{t \in [0, T]}$ is adapted to B .

New notation: $df(t, B_t) = [D_x f](t, B_t) dB_t + \left\{ [D_t f](t, B_t) + \frac{1}{2} [D_x^2 f](t, B_t) \right\} dt$

or $dX_t := V_t dB_t + D_t dt$. + initial condition