

Reminder VIII

standard 1D Brownian motion

• Aim : define $\int_a^b X_t dB_t$

↖ adapted univariate stochastic process

• Discrete time version : $(X_n)_{n \in \mathbb{N}}$ predictable

$$(X \cdot M)_n := X_0 M_0 + \sum_{j=1}^n X_j (M_j - M_{j-1})$$

↖ martingale transform if M a martingale

$((X \cdot M)_n)_{n \in \mathbb{N}}$ is a martingale if $(M_n)_{n \in \mathbb{N}}$ is a martingale.

• Continuous time version = Itô integral

1° $M_{loc}^p([a,b])$, $M^p([a,b])$ progressively measurable + univariate + regularity

2° Elementary processes ("constant" on time intervals)

$$3° \int_a^b X_t dB_t = \sum_{j=0}^{n-1} X_j (B_{t_{j+1}} - B_{t_j})$$

↖ variance

Properties, if $X \in M^2([a,b])$, 0 expectation + isometry

4° For general $X \in M_{loc}^2([a,b])$

$$\int_a^b X_t dB_t = \lim_{n \rightarrow \infty} \int_a^b X_{n,t} dB_t$$

↖ elementary processes

↖ limit in a suitable sense

• Set $Y_t := \int_0^t X_u dB_u$ for $t \in [0, T]$.

↖ adapted to the filtration

If $X \in M^2([0, T])$, then $(Y_t)_{t \in [0, T]}$ a martingale

with 0 expectation and $E(Y_t^2) = \int_0^t E(X_u^2) du < \infty$

↖ variance