

Discrete Convexity and Polynomial Solvability in Minimum 0-Extension Problems

Hiroshi HIRAI

The University of Tokyo

hirai@mist.i.u-tokyo.ac.jp

<http://www.misojiro.t.u-tokyo.ac.jp/~hirai/>

Combinatorial Geometries

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1. Minimum 0-extension problem
 \simeq Multifacility location problem
2. Known results on P/NP-hard classification
3. Main result (SODA'13)
4. Proof idea \sim
 - Metric graph theory (Bandelt, Chepoi, Dress, Van de Vel, ...)
 - Discrete convex analysis (Murota 1996 \sim)
 - Valued CSP & fractional polymorphism (Thapper-Živný 2012)

Multifacility location problem (70's ~)

Γ : undirected graph

d_Γ : path-metric on V_Γ

y_1, y_2, \dots, y_k : existing facilities on Γ

Locate new facilities x_1, x_2, \dots, x_n on Γ such that the mutual *communication cost* between facilities

$$\underbrace{\sum_{i,j} b_{ij} d_\Gamma(x_i, y_j)}_{\text{cost between new and old}} + \underbrace{\sum_{i < j} c_{ij} d_\Gamma(x_i, x_j)}_{\text{cost between new facilities}}$$

is minimum.

Recent applications: clustering, learning theory, computer vision, ...
c.f. *Metric Labeling* (Kleinberg-Tardos 1998)

$$V_\Gamma = \{v_1, v_2, \dots, v_k\}$$

Input: number n of variables, $b_{ij}, c_{ij} \geq 0$

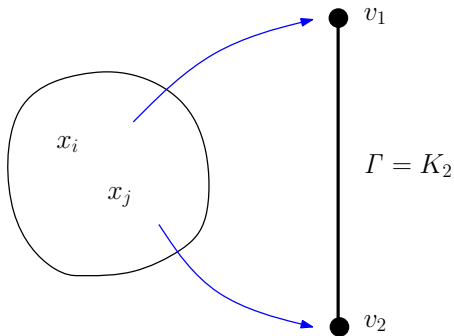
$$\begin{aligned} \mathbf{MultiFac}[\Gamma] : \quad & \text{Min.} \quad \sum_{i,j} b_{ij} d_\Gamma(x_i, v_j) + \sum_{i < j} c_{ij} d_\Gamma(x_i, x_j) \\ & \text{s.t.} \quad (x_1, x_2, \dots, x_n) \in V_\Gamma \times V_\Gamma \times \dots \times V_\Gamma \end{aligned}$$

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Ex. $\Gamma = K_2$

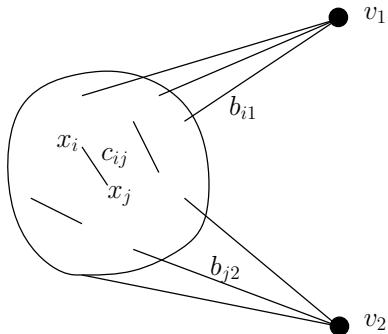


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Ex. $\Gamma = K_2$



$\text{MultiFac}[K_2] \simeq \text{Minimum } (v_1, v_2)\text{-cut}$

Tractability Question (Chepoi 1996, Karzanov 1998, 2004)

$\Gamma = K_2 \Leftrightarrow$ minimum cut $\Rightarrow P$ (Ford-Fulkerson 1956)

$\Gamma = K_{n \geq 3} \Leftrightarrow$ multi-terminal cut \Rightarrow **NP-hard**
(Dahlhaus, Johnson, Papadimitriou, Seymour, Yannakakis 1994)

Question

What is Γ for which **MultiFac** $[\Gamma]$ is in P ?

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Known tractable class:

- Trees (Picard-Ratliff 1978)
- Median graphs (Chepoi 1996)
- Frames (Karzanov 1998)

Theorem (Picard-Ratliff 1978)

If Γ is a tree, then **MultiFac** $[\Gamma]$ is in P.

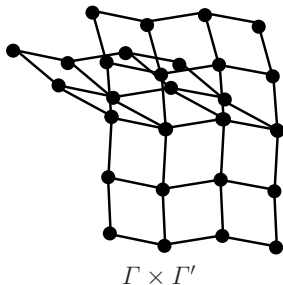
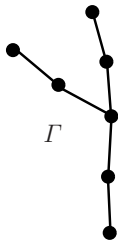
Theorem (Picard-Ratliff 1978)

If Γ is a tree, then $\mathbf{MultiFac}[\Gamma]$ is in \mathbf{P} .

Obs. $\Gamma \in \mathbf{P}$ and $\Gamma' \in \mathbf{P} \Rightarrow \Gamma \times \Gamma' \in \mathbf{P}$

$$\because d_{\Gamma \times \Gamma'}((x, x'), (y, y')) = d_{\Gamma}(x, y) + d_{\Gamma'}(x', y')$$

$$\rightarrow \mathbf{MultiFac}[\Gamma \times \Gamma'] = \mathbf{MultiFac}[\Gamma] + \mathbf{MultiFac}[\Gamma']$$

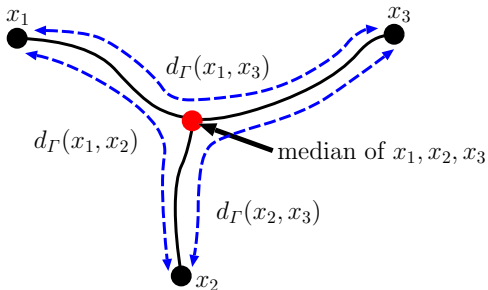


Cor. cube, grid graph, product of trees $\in \mathbf{P}$

- **Median** of $x_1, x_2, x_3 \Leftrightarrow y \in V_\Gamma$ satisfying

$$d_\Gamma(x_i, x_j) = d_\Gamma(x_i, y) + d_\Gamma(y, x_j) \quad (1 \leq i < j \leq 3)$$

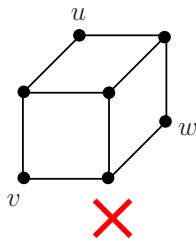
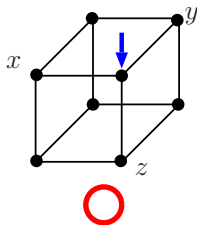
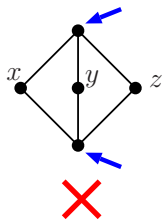
- **Median graph** $\Leftrightarrow \forall$ triple has a *unique* median.



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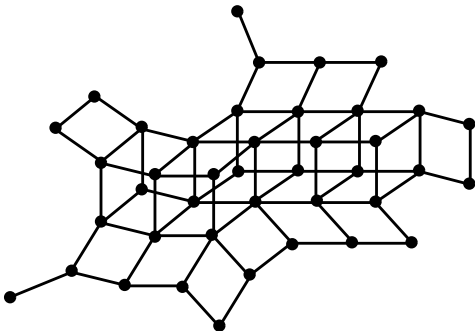


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c.f. median graph \simeq graph of CAT(0) cube complex (Chepoi 2000)

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- **Median graph** $\Leftrightarrow \forall$ triple has a *unique* median.

Theorem (Chepoi 1996)

If Γ is a median graph, then **MultiFac** $[\Gamma]$ is in **P**.

\therefore use of minimum cut

0-extension formulation (Karzanov 1998)

(V, μ) : finite metric space

Def: *extension* of (V, μ)

\Leftrightarrow metric space (X, d) s.t. $X \supseteq V$ and $d|_V = \mu$

Def: *0-extension* of (V, μ)

\Leftrightarrow extension (X, d) s.t. $\forall x \in X, \exists s \in V : d(x, s) = 0$.

$\Leftrightarrow d = \mu \circ \rho$ for some retraction $\rho : X \rightarrow V$.

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Obs. **Multifac** $[I] \simeq$

$$\begin{array}{ll} \mathbf{0-Ext}[I]: & \text{Min.} \quad \sum_{x,y} c_{xy} d(x,y) \\ & \text{s.t.} \quad (X, d) \text{ is a 0-extension of } (V_I, d_I) \end{array}$$

$\therefore (\{v_1, v_2, \dots, v_k\}, d_I) \rightarrow (\{v_1, v_2, \dots, v_k, x_1, x_2, \dots, x_n\}, d)$

$$\begin{array}{ll} \mathbf{0-Ext}[\Gamma] : & \text{Min.} \quad \sum_{xy} c_{xy} d(x, y) \\ & \text{s.t.} \quad (X, d): \text{0-extension of } (V_\Gamma, d_\Gamma) \end{array}$$

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Metric-LP relaxation (Karzanov 98)

$$\begin{array}{ll} \mathbf{Ext}[\Gamma] : & \text{Min.} \quad \sum_{xy} c_{xy} d(x, y) \\ & \text{s.t.} \quad d(x, x) = 0 \\ & \quad \quad d(x, y) = d(y, x) \geq 0 \\ & \quad \quad d(x, y) + d(y, z) \geq d(x, z) \\ & \quad \quad d|_{V_\Gamma} = d_\Gamma \end{array}$$

Rem: $\mathbf{Ext}[\Gamma]$ is polysize LP \rightarrow P

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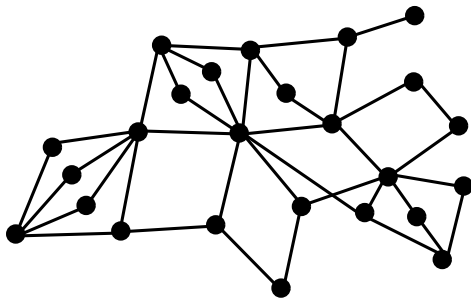
Q. *What is Γ for which $\mathbf{Ext}[\Gamma]$ is exact ?*

c.f. LP-dual of multicommodity flow (Karzanov 1998, H. 2009 ~)

Frame = graph for which $\text{Ext}[\Gamma]$ is exact

Γ : frame \Leftrightarrow

- bipartite
- no isometric cycle of length > 4
- *orientable* $\Leftrightarrow \exists$ orientation: \forall 4-cycle

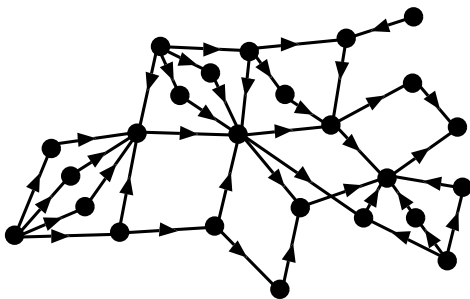


Rem: frame is obtained by *gluing* $K_{2,m}$ and K_2 (in a certain way)

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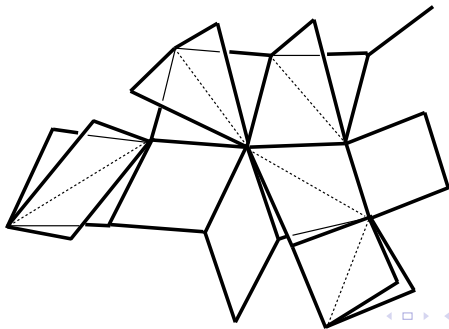
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c.f. frame \simeq CAT(0)-complex of *folders* (Chepoi 2000)



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Theorem (Karzanov 1998)

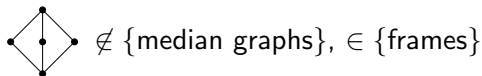
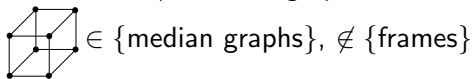
Γ is a frame if and only if $\mathbf{Ext}[\Gamma] = \mathbf{0-Ext}[\Gamma]$.

Corollary (Karzanov 1998)

If Γ is a frame, then $\mathbf{MultiFac}[\Gamma]$ ($= \mathbf{0-Ext}[\Gamma]$) is in \mathbf{P} .

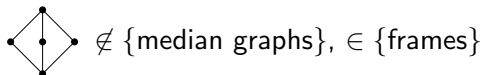
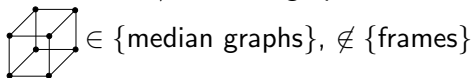
Rem. $\{\text{frames}\}$ is not closed under product

Rem. $\text{frame} \neq \text{median graph}$



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• Γ : *modular* $\Leftrightarrow \forall$ triple has a median.

• Γ : *orientable* $\Leftrightarrow \exists$ orientation: \forall 4-cycle



Rem. $\text{frame} = \text{orientable hereditary modular graph}$ (c.f. Bandelt 85)

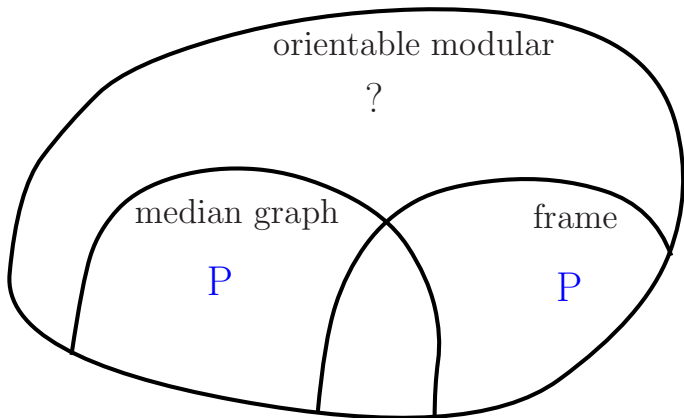
Ex. Hasse diagram of modular lattice

Hardness result

Theorem (Karzanov 1998)

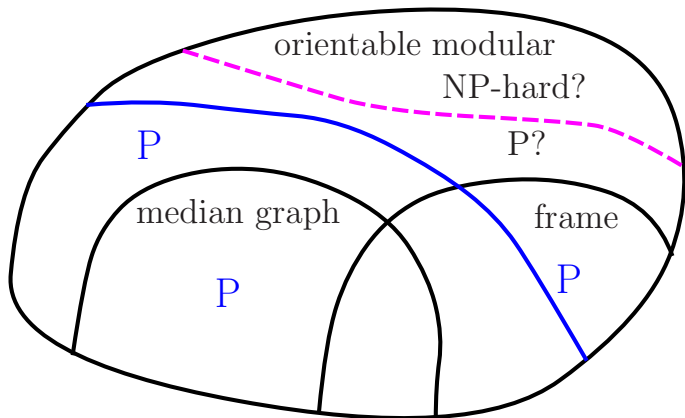
If Γ is not modular or not orientable, **MultiFac** $[\Gamma]$ is **NP-hard**.

NP-hard



Partial result & conjectures (Karzanov 2004)

NP-hard



Main result

Theorem (H. 2012; SODA'13)

If Γ is orientable modular, then **MultiFac** $[\Gamma]$ is in **P**.

NP-hard

orientable modular

P

$$\begin{aligned} \mathbf{MultiFac}[\Gamma] : \quad & \text{Min.} \quad \sum_{i,j} b_{ij} d_{\Gamma}(x_i, v_j) + \sum_{i < j} c_{ij} d_{\Gamma}(x_i, v_j) \\ & \text{s.t.} \quad (x_1, x_2, \dots, x_n) \in V_{\Gamma} \times V_{\Gamma} \times \dots \times V_{\Gamma} \end{aligned}$$

Basic idea \sim formulate **MultiFac** as a 'convex' optimization over a *simplicial complex* associated with orientable modular graph, based on a philosophy of *Discrete Convex Analysis*.

A theory of 'convex' functions on $\mathbf{Z}^n = \mathbf{Z} \times \mathbf{Z} \times \cdots \times \mathbf{Z}$ for well-solvable combinatorial optimization problems including *network flows*, *matroids*, and *submodular functions*.

Obs. If $\Gamma = \text{path}$, then $\Gamma \times \Gamma \times \cdots \times \Gamma \simeq \text{box } B$ in \mathbf{Z}^n ,

$$\text{Min.} \quad \sum_{i,j} b_{ij} d_{\Gamma}(x_i, v_j) + \sum_{i < j} c_{ij} d_{\Gamma}(x_i, x_j)$$

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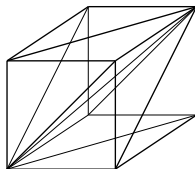
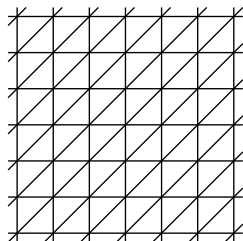
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$$\begin{aligned} \text{Min.} \quad & \sum_{i,j} b_{ij} |x_i - v_j| + \sum_{i < j} c_{ij} |x_i - x_j| \\ \text{s.t.} \quad & (x_1, x_2, \dots, x_n) \in B \subseteq \mathbf{Z}^n \end{aligned}$$

→ This is an L-convex function minimization in DCA

L-convex functions (for combinatorial geometers)

Triangulation Δ of \mathbf{Z}^n diced by hyperplanes of normal $e_i, e_i - e_j$



Def: A function g on \mathbf{Z}^n is L-convex

\Leftrightarrow piecewise-linear interpolation of g w.r.t. Δ is convex in \mathbf{R}^n .

Lovász extension of g

- L-convex function is minimized by tracing the 1-skeleton of Δ
 - Descent direction is found by *Submodular Function Minimization*
- $f : \{0, 1\}^n \rightarrow \mathbf{R}$ is submodular if $f(x) + f(y) \geq f(x \vee y) + f(x \wedge y)$

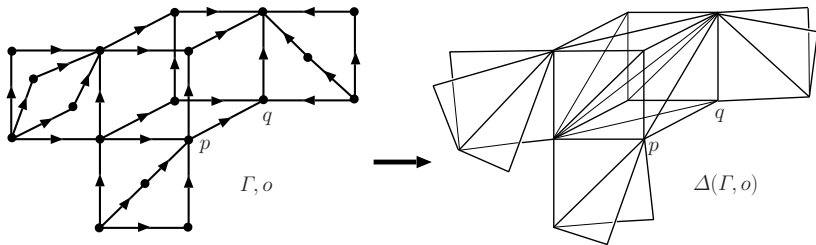
We develop an analogous theory for orientable modular graph Γ
(with orientation o)

Fact: o.m.graph is obtained by *gluing geometric modular lattices*

- Median graph \leftrightarrow Boolean lattices
- Frame \leftrightarrow diamonds (geometric modular lattices of rank 2)

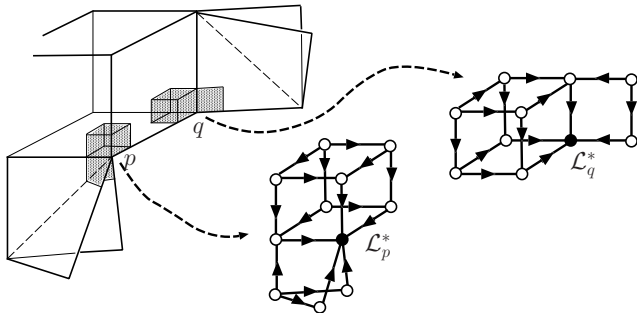
Def: *Modular complex* $\Delta(\Gamma)$

:= union of order complexes of these lattices



$g : V_\Gamma \rightarrow \mathbf{R} \implies$ piecewise-linear interpolation $\bar{g} : \Delta(\Gamma) \rightarrow \mathbf{R}$

Neighborhood \mathcal{L}_p^* of $p \in V_\Gamma$ in $\Delta(\Gamma)$
 \simeq *modular semilattice* (Bandelt, Van de Vel, Verheul 1993)



- define *submodular function* on modular semilattice [Appendix 1]
- $g : V_\Gamma \rightarrow \mathbf{R}$ is *L-convex* if \bar{g} is submodular on \mathcal{L}_p^* ($\forall p \in V_\Gamma$)

- L-convex function is minimized by tracing 1-skeleton of Δ .
- Descent direction is found by SFM on a modular semilattice.
- d_Γ is L-convex on $\Gamma \times \Gamma$.
- **MultiFac** $[\Gamma]$ is L-convex minimization on $\Gamma \times \Gamma \times \dots \times \Gamma$.

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Thapper-Živný fractional polymorphism criterion in Valued-CSP (FOCS'12) is applicable.

[Appendix 2]

Minimizing a sum of submodular functions of *bounded arity* in \mathcal{P}

Our problem is minimizing a sum of arity-2 submodular functions.

→ **MultiFac** $[\Gamma]$ in \mathcal{P}

Question

What is Γ for which **MultiFac** $[\Gamma]$ is in P ?

Answer

$$\mathbf{MultiFac}[\Gamma] \in \begin{cases} P & \text{if } \Gamma \text{ is } \mathbf{orientable modular} \\ \mathbf{NP-hard} & \text{otherwise} \end{cases}$$

Many interesting aspects:

- Submodularity/L-convexity for multicommodity flows
→ multiflow analogue of [Max-flow = Min-cut \in SFM]
- Modular lattices, and modular semilattices
- Dichotomy theorem in Valued-CSP
- Optimization theory on CAT(0)-complex ??

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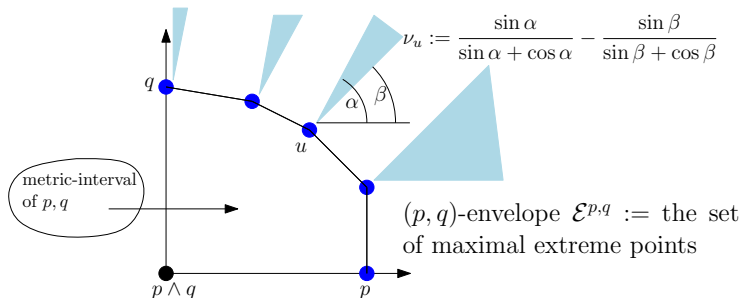
Thank you for your attention !

Appendix 1: Modular semilattice & submodular function

Meet-semilattice \mathcal{L} is **modular** \Leftrightarrow

- every lower ideal is a modular lattice
- $u \vee v, v \vee w, w \vee u \in \mathcal{L} \Rightarrow u \vee v \vee w \in \mathcal{L}$

• We can define a fractional join $\sum \{\nu_u u \mid u \in \mathcal{E}^{p,q}\}$.



Def: f is **submodular** if $f(p) + f(q) \geq f(p \wedge q) + \sum_{u \in \mathcal{E}^{p,q}} \nu_u f(u)$

Appendix 2: Valued-CSP & fractional polymorphism

Λ : a set of functions f on D with arity K

$$\begin{array}{ll} \mathbf{VCSP}[\Lambda]: & \text{Min.} \quad \sum_{f \in \Lambda; i_1, i_2, \dots, i_K} c_{i_1, i_2, \dots, i_K}^f f(x_{i_1}, x_{i_2}, \dots, x_{i_K}) \\ & \text{s.t.} \quad (x_1, x_2, \dots, x_N) \in D \times D \times \dots \times D \end{array}$$

\simeq Minimization of a sum of functions with *bounded arity*

- Input size = $O(|\Lambda||D|^K)$
- **VCSP** has polysize IP formulation \rightarrow Basic LP-relaxation

Theorem (Thapper-Živný, FOCS'12)

VCSP $[\Lambda] = \text{Basic LP} \in \mathbf{P}$

if Λ has a fractional polymorphism \ni semilattice operation

Def: *fractional polymorphism* for Λ

\Leftrightarrow probability ω on the *space of operations* $\{g : D \times D \rightarrow D\}$:

$$(f(p) + f(q))/2 \geq \sum_g \omega(g) f(g(p, q)) \quad (\forall f \in \Lambda, \forall (p, q)).$$