

Linear algebra I, autumn term 2018

Solutions to Homework 5

$$\begin{aligned} \text{1a) } A &= \begin{pmatrix} 1 & 0 & 1 & 1 \\ 7 & 7 & 8 & 0 \\ 1 & 2 & 1 & -1 \\ 7 & 7 & 6 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 1 & 1 \\ 0 & 7 & 1 & -7 \\ 0 & 2 & 0 & -2 \\ 0 & 7 & -1 & -7 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 1 & 1 \\ 0 & 2 & 0 & -2 \\ 0 & 7 & 1 & -7 \\ 0 & 7 & -1 & -7 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & -1 \\ 0 & 7 & 1 & -7 \\ 0 & 7 & -1 & -7 \end{pmatrix} \\ &\sim \begin{pmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 6 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} = \text{rref}(A). \end{aligned}$$

There are pivot elements in col. 1, 2 and 3 of $\text{rref}(A)$, hence

$$u_1 = Ae_1 = \begin{pmatrix} 1 \\ 7 \\ 1 \\ 7 \end{pmatrix}, \quad u_2 = Ae_2 = \begin{pmatrix} 0 \\ 7 \\ 2 \\ 7 \end{pmatrix}, \quad u_3 = Ae_3 = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 6 \end{pmatrix} \text{ form a basis of } \text{im} A.$$

Apply the Gram-Schmidt algorithm to obtain an orthonormal basis $f = (f_1, f_2, f_3)$ from (u_1, u_2, u_3) :

$$f_1 = \frac{1}{\|u_1\|} u_1 = \frac{1}{10} \begin{pmatrix} 1 \\ 7 \\ 1 \\ 7 \end{pmatrix}.$$

$$w_2 = u_2 - (u_2 \cdot f_1) f_1 = \begin{pmatrix} 0 \\ 7 \\ 2 \\ 7 \end{pmatrix} - \frac{100}{10} \cdot \frac{1}{10} \begin{pmatrix} 1 \\ 7 \\ 1 \\ 7 \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$f_2 = \frac{1}{\|w_2\|} w_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix}.$$

$$w_3 = u_3 - (u_3 \cdot f_1) f_1 - (u_3 \cdot f_2) f_2 = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 6 \end{pmatrix} - \frac{100}{10} \cdot \frac{1}{10} \begin{pmatrix} 1 \\ 7 \\ 1 \\ 7 \end{pmatrix} - 0 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ -1 \end{pmatrix}$$

$$f_3 = \frac{1}{\|w_3\|} w_3 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ 0 \\ -1 \end{pmatrix}.$$

The vectors f_1, f_2, f_3 form an orthonormal basis of $\text{im} A$.

b) To find an orthonormal basis $g = (g_1, g_2, g_3, g_4)$ of \mathbb{R}^4 that extends \underline{f} , let $g_1 = f_1$, $g_2 = f_2$ and $g_3 = f_3$.

Then we need $g_4 \cdot f_1 = g_4 \cdot f_2 = g_4 \cdot f_3 = 0$, in other words, $g_4 \in \text{span}\{f_1, f_2, f_3\}^\perp = (\text{im } F)^\perp = \ker A^T$, and $\|g_4\| = 1$.

$$\begin{aligned} A^T &= \begin{pmatrix} -1 & 1 & 7 & 1 & 7 \\ 0 & 7 & 2 & 7 \\ 1 & 8 & 1 & 6 \\ 1 & 0 & -1 & 0 \end{pmatrix} \sim \begin{pmatrix} -1 & 1 & 7 & 1 & 7 \\ 0 & 7 & 2 & 7 \\ 0 & 1 & 0 & -1 \\ 0 & -7 & -2 & -7 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 7 & 2 & 7 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 0 & 2 & 14 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \\ &\sim \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 0 & 1 & 7 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 0 & 7 \\ 0 & 0 & 1 & 7 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 0 & 7 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 7 \\ 0 & 0 & 0 & 0 \end{pmatrix} = \text{ref}(A^T) \end{aligned}$$

$$\text{Hence } A^T x = 0 \Leftrightarrow \begin{cases} x_1 + 7x_4 = 0 \\ x_2 - x_4 = 0 \\ x_3 + 7x_4 = 0 \end{cases} \quad \text{Set } x_4 = t, \quad x = t \begin{pmatrix} -7 \\ 1 \\ -7 \\ 1 \end{pmatrix}, \quad t \in \mathbb{R}.$$

$$(\text{im } F)^\perp = \text{span} \left\{ \begin{pmatrix} -7 \\ 1 \\ -7 \\ 1 \end{pmatrix} \right\}.$$

$$\text{So } g_4 \in \text{span} \left\{ \begin{pmatrix} -7 \\ 1 \\ -7 \\ 1 \end{pmatrix} \right\}, \quad \|g_4\| = 1.$$

$$\text{Define } g_4 = \frac{1}{\left\| \begin{pmatrix} -7 \\ 1 \\ -7 \\ 1 \end{pmatrix} \right\|} \begin{pmatrix} -7 \\ 1 \\ -7 \\ 1 \end{pmatrix} = \frac{1}{10} \begin{pmatrix} -7 \\ 1 \\ -7 \\ 1 \end{pmatrix}.$$

$$\text{Then } g_4 \in \text{span} \left\{ \begin{pmatrix} -7 \\ 1 \\ -7 \\ 1 \end{pmatrix} \right\} = (\text{im } F)^\perp \implies g_1 \cdot g_4 = g_2 \cdot g_4 = g_3 \cdot g_4 = 0, \quad \|g_4\| = 1.$$

Hence $g = (g_1, g_2, g_3, g_4)$ is an orthonormal basis of \mathbb{R}^4 , extending \underline{f} .

$$\left(g_1 = \frac{1}{10} \begin{pmatrix} 1 \\ 7 \\ 1 \\ 7 \end{pmatrix}, g_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, g_3 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ 0 \\ -1 \end{pmatrix}, g_4 = \frac{1}{10} \begin{pmatrix} -7 \\ 1 \\ -7 \\ 1 \end{pmatrix} \right)$$

2) Define a linear map $F: \mathbb{R}^3 \rightarrow \mathbb{R}^4$ by $\begin{pmatrix} a \\ b \\ c \end{pmatrix} \mapsto \begin{pmatrix} f(0) \\ f(1) \\ f(2) \\ f(3) \end{pmatrix}$

$$\text{where } f(t) = a + b \cos \frac{\pi t}{2} + c \sin \frac{\pi t}{2}.$$

Then the least square approximation of the points $(0, y_0), (1, y_1), (2, y_2), (3, y_3)$

is given by $f(t) = \alpha + \beta \cos \frac{\pi t}{2} + \gamma \sin \frac{\pi t}{2}$, where $\begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix} = x$ is

a solution to the equation $A^T A x = A^T b$, for $A = [F]$ and $b = \begin{pmatrix} y_0 \\ y_1 \\ y_2 \\ y_3 \end{pmatrix}$.

$$F(e_1) = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \quad F(e_2) = \begin{pmatrix} \cos(0) \\ \cos \frac{\pi}{2} \\ \cos \pi \\ \cos \frac{3\pi}{2} \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix}, \quad F(e_3) = \begin{pmatrix} \sin(0) \\ \sin \frac{\pi}{2} \\ \sin \pi \\ \sin \frac{3\pi}{2} \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \\ -1 \end{pmatrix}$$

$$\Rightarrow A = [F] = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & -1 & 0 \\ 1 & 0 & -1 \end{pmatrix}$$

$$A^T A = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & -1 & 0 \\ 1 & 0 & -1 \end{pmatrix} = \begin{pmatrix} 4 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$A^T b = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \end{pmatrix} \begin{pmatrix} y_0 \\ y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} y_0 + y_1 + y_2 + y_3 \\ y_0 - y_2 \\ y_1 - y_3 \end{pmatrix}$$

$$\text{Hence, } A^T A x = A^T b \iff x = \begin{pmatrix} (y_0 + y_1 + y_2 + y_3)/4 \\ (y_0 - y_2)/2 \\ (y_1 - y_3)/2 \end{pmatrix}.$$

The least-square approximation of the points is

$$\underline{\underline{f(t) = \frac{y_0 + y_1 + y_2 + y_3}{4} + \frac{y_0 - y_2}{2} \cos \frac{\pi t}{2} + \frac{y_1 - y_3}{2} \sin \frac{\pi t}{2}}}$$

3) Assume that $\underline{u} = (u_1, \dots, u_r)$ and $\underline{v} = (v_1, \dots, v_s)$ are bases of U and U^\perp , respectively.

By results from the lectures, we know that every $x \in \mathbb{R}^n$ can be written as $x = x_{\parallel} + x_{\perp}$ for some $x_{\parallel} \in U$, $x_{\perp} \in U^\perp$.

Hence, $x_{\parallel} \in \text{span } \underline{u} \subset \text{span}(\underline{u} \cup \underline{v})$ and $x_{\perp} \in \text{span } \underline{v} \subset \text{span}(\underline{u} \cup \underline{v})$
 $\implies x = x_{\parallel} + x_{\perp} \in \text{span}(\underline{u} \cup \underline{v})$.

To show that $\underline{u} \cup \underline{v}$ is linearly independent, assume that $\lambda_1 u_1 + \dots + \lambda_r u_r + \mu_1 v_1 + \dots + \mu_s v_s = 0$, where $\lambda_1, \dots, \lambda_r, \mu_1, \dots, \mu_s \in \mathbb{R}$.

Then $\underbrace{\lambda_1 u_1 + \dots + \lambda_r u_r}_{\in \text{span } \underline{u}} = \underbrace{-\mu_1 v_1 - \mu_2 v_2 - \dots - \mu_s v_s}_{\in \text{span } \underline{v}} \in (\text{span } \underline{u}) \cap (\text{span } \underline{v}) = U \cap U^\perp = \{0\}$

Hence $\lambda_1 u_1 + \dots + \lambda_r u_r = 0 \implies \lambda_1 = \dots = \lambda_r = 0$,

and $\mu_1 v_1 + \dots + \mu_s v_s = 0 \implies \mu_1 = \dots = \mu_s = 0$

since \underline{u} and \underline{v} each is linearly independent.

Thus, $\underline{u} \cup \underline{v} = (u_1, \dots, u_r, v_1, \dots, v_s)$ is linearly independent.

This proves that $\underline{u} \cup \underline{v}$ is a basis of \mathbb{R}^n .