

Reminder III

- Special Gaussian probability distribution : $\mathbf{0} = N(\mathbf{0}, \mathbf{0})$.
- Gaussian vector X if $a \cdot X$ is a Gaussian r.v.
($\equiv X_1, \dots, X_N$ jointly Gaussian).
- X Gaussian vector $\Leftrightarrow \mathbb{E}(e^{a \cdot X}) = \exp(a \cdot \mathbb{E}(X) + a^T \text{Cov}(X) a)$
 $\forall a \in \mathbb{R}^N$. *ms importance of mean value + covariance matrix*
- X non-degenerate if $\det(\text{Cov}(X)) \neq 0$.
 $\Leftrightarrow a \cdot X = 0 \Rightarrow a = 0 \in \mathbb{R}^N$ *linear independence*
- Joint prob. distribution of non-degenerate Gaussian vector
$$\pi_X(x) = \frac{1}{(2\pi)^{N/2} |P|^{1/2}} \exp\left(-\frac{1}{2}(x - \bar{x})^T P^{-1}(x - \bar{x})\right)$$

$P = \text{Cov}(X)$ $\uparrow \mathbb{E}(X)$
- $(X_t)_{t \in T}$ with $X_t : \Omega \rightarrow \Lambda$ family of random variables.
- Gaussian process if $(X_{t_1}, X_{t_2}, \dots, X_{t_n})$ Gaussian vector
some authors assume it non-degenerate, some not \rightarrow
- $\forall t_j \in T, t_j < t_{j+1}$. *ms Examples defined by $\mathbb{E} + \text{Cov}$*
- Filtration $(\mathcal{F}_t)_{t \in T}$ family of σ -subalgebras of \mathcal{F} .
- Stochastic process $X = (\Omega, \mathcal{F}, \mathbb{P}, (\mathcal{F}_t)_{t \in T}, (X_t)_{t \in T})$
 $X_t : \Omega \rightarrow \Lambda$ \mathcal{F}_t -measurable.