

# Heisenberg Group

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## 1 Introduction

This report aims to introduce the Heisenberg group  $H$  named after Werner Heisenberg and solves relevant exercises.

## 2 Definition

The Heisenberg group  $H$  is the group of  $3 \times 3$  upper triangular matrices  $A$  of the form

$$A = \begin{pmatrix} 1 & a_1 & a_2 \\ 0 & 1 & a_3 \\ 0 & 0 & 1 \end{pmatrix} \quad (1)$$

where  $a_1, a_2$  and  $a_3$  are arbitrary real numbers. It is clearly associative as it is a group of matrices.

Let  $B$  also take the form

$$B = \begin{pmatrix} 1 & b_1 & b_2 \\ 0 & 1 & b_3 \\ 0 & 0 & 1 \end{pmatrix} \quad (2)$$

where  $b_i$  ( $i = 1, 2, 3$ )  $\in \mathbb{R}$ . And  $AB$  is written as

$$AB = \begin{pmatrix} 1 & a_1 + b_1 & b_2 + a_1 b_3 + a_2 \\ 0 & 1 & a_3 + b_3 \\ 0 & 0 & 1 \end{pmatrix} \quad (3)$$

It is easy to check that the product of two matrices  $AB$  is again of the form (1). and it is clear that the identity matrix is of the form (1) by substituting zero to  $a_1, a_2, a_3$ .

Furthermore, a direct computation shows that if  $A$  is as in (1), then

$$A^{-1} = \begin{pmatrix} 1 & -a_1 & a_1 a_3 - a_2 \\ 0 & 1 & -a_3 \\ 0 & 0 & 1 \end{pmatrix} \quad (4)$$

It can be checked that  $AA^{-1} = A^{-1}A = I$ .

Therefore,  $H$  is a subgroup of  $GL(3; \mathbb{R})$ . In fact,  $H$  is also a matrix Lie group.

### 3 Exercises

Exercise 1

Determine the center  $Z(H)$  of the Heisenberg group  $H$ . Show that the quotient group  $H/Z(H)$  is abelian.

From Definition 1.2.11 in the lecture notes, the center of a Lie group  $H$  is defined by

$$Z(H) = \{A \in H \mid AB = BA \text{ for all } B \in H\} \quad (5)$$

Using eq.(3),  $AB = BA$  is written as

$$\begin{pmatrix} 1 & a_1 + b_1 & b_2 + a_1b_3 + a_2 \\ 0 & 1 & a_3 + b_3 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & a_1 + b_1 & b_2 + a_3b_1 + a_2 \\ 0 & 1 & a_3 + b_3 \\ 0 & 0 & 1 \end{pmatrix} \quad (6)$$

From this, one can obtain

$$a_1b_3 = a_3b_1 \quad (7)$$

this equation is satisfied for any real numbers  $b_1, b_2, b_3$  only when  $a_1$  and  $a_3$  are zero. Therefore  $Z(H)$  can be given by

$$Z(H) = \left\{ \begin{pmatrix} 1 & 0 & a \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \mid a \in \mathbb{R} \right\} \quad (8)$$

From now on, let us show that the quotient group  $H/Z(H)$  is abelian. This group is defined by

$$H/Z(H) = \{[A] = AZ(H) = Z(H)A \mid A \in H\} \quad (9)$$

where  $Z(H)$  is an abelian and normal subgroup of  $H$  from the exercise 1.2.12. It is sufficient to consider the left coset.  $H/Z(H)$  is abelian if and only if  $[A][B] = [B][A]$  for any  $A, B \in H$ . By definition, one has

$$\begin{aligned} [A][B] &= [AB] \\ &= ABZ(H) \\ &= \left\{ AB \begin{pmatrix} 1 & 0 & a \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \mid a \in \mathbb{R} \right\} \\ &= \left\{ \begin{pmatrix} 1 & a_1 & a_2 \\ 0 & 1 & a_3 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & b_1 & b_2 \\ 0 & 1 & b_3 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & a \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \mid a \in \mathbb{R} \right\} \\ &= \left\{ \begin{pmatrix} 1 & a_1 + b_1 & a + (a_2 + b_2) + a_1b_3 \\ 0 & 1 & a_3 + b_3 \\ 0 & 0 & 1 \end{pmatrix} \mid a \in \mathbb{R} \right\} \\ &= \left\{ \begin{pmatrix} 1 & a_1 + b_1 & c \\ 0 & 1 & a_3 + b_3 \\ 0 & 0 & 1 \end{pmatrix} \mid c \in \mathbb{R} \right\} \end{aligned} \quad (10)$$

Likewise,

$$\begin{aligned}
[B][A] &= [BA] \\
&= \left\{ \begin{pmatrix} 1 & a_1 + b_1 & a + (a_2 + b_2) + b_1 a_3 \\ 0 & 1 & a_3 + b_3 \\ 0 & 0 & 1 \end{pmatrix} \mid a \in \mathbb{R} \right\} \\
&= \left\{ \begin{pmatrix} 1 & a_1 + b_1 & c \\ 0 & 1 & a_3 + b_3 \\ 0 & 0 & 1 \end{pmatrix} \mid c \in \mathbb{R} \right\}
\end{aligned} \tag{11}$$

As shown above, it is possible to use  $c \in \mathbb{R}$  as (1,3) element since  $a$  can take any real number. It is confirmed from equation (10) and (11) that  $[A][B] = [B][A]$  and thus  $H/Z(H)$  is abelian.

Exercise 2

Show that the exponential mapping from the Lie algebra of the Heisenberg group to the Heisenberg group is one-to-one and onto.

By definition, one has for  $t \in \mathbb{R}$

$$e^{tX} = \sum_{j=0}^{\infty} \frac{(tX)^j}{j!} \tag{12}$$

Let us compute  $e^{tX}$ , where

$$tX = \begin{pmatrix} 0 & tx & ty \\ 0 & 0 & tz \\ 0 & 0 & 0 \end{pmatrix} \tag{13}$$

with any  $x, y, z \in \mathbb{R}$ . Note that

$$(tX)^2 = \begin{pmatrix} 0 & 0 & t^2xz \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

and that

$$(tX)^3 = 0$$

Therefore,

$$\begin{aligned}
e^{tX} &= \frac{(tX)^0}{0!} + \frac{(tX)^1}{1!} + \frac{(tX)^2}{2!} + \sum_{j=3}^{\infty} \frac{(tX)^j}{j!} \\
&= \begin{pmatrix} 1 & tx & ty + t^2xz/2 \\ 0 & 1 & tz \\ 0 & 0 & 1 \end{pmatrix}
\end{aligned} \tag{14}$$

By definition, the Lie algebra of  $H$  denoted  $L(H)$  is the set of all matrices  $Y$  such that  $e^{tY}$  is in  $H$  for all real numbers  $t$ .

$$L(H) = \{Y \mid e^{tY} \in H \text{ for all } t \in \mathbb{R}\} \tag{15}$$

Thus the matrix  $X$  is in  $L(H)$  as  $e^{tX} \in H$  for any  $t \in \mathbb{R}$ .

Let us now consider the exponential mapping from some element  $X \in L(H)$  to  $e^X \in H$ .

**Surjective proof:**

The component  $x, z$  in  $X$  (eq.(13)) can take any real number, so the (1,2) and (2,3) elements in  $e^X$  (eq.(14)) can trivially be any real number. It is also clear that the element  $y+xz/2$  can be any real number as  $y$  can take any real number for any fixed  $x, z$ . Therefore this mapping is surjective.

**Injective proof:**

Let  $X'$  denote  $X$  replacing  $x, y, z$  with  $x', y', z'$  and suppose  $e^X = e^{X'}$ , that is

$$\begin{aligned} x &= x' \\ y + xz/2 &= y' + x'z'/2 \\ z &= z' \end{aligned}$$

One can also derive  $y = y'$  as it is clear that  $xz/2 = x'z'/2$  from  $x = x', z = z'$ . It is finally confirmed that  $X = X'$ , which satisfies the condition for injective.

From the discussion above, it is proved that the exponential mapping from  $X \in L(H)$  to  $e^X \in H$  is bijective.

## 4 Application in physics

The following three elements form a basis for the Lie algebra of the Heisenberg group  $L(H)$

$$X = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}; Y = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}; Z = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad (16)$$

It is known that these basis elements satisfy the commutation relations,

$$[X, Y] = Z; [X, Z] = 0; [Y, Z] = 0 \quad (17)$$

The name "Heisenberg group" is motivated by the preceding relations, which have the same form as the canonical commutation relations in quantum mechanics,

$$[\hat{x}, \hat{p}] = i\hbar I; [\hat{x}, i\hbar I] = 0; [\hat{p}, i\hbar I] = 0 \quad (18)$$

where  $\hat{x}$  is the position operator,  $\hat{p}$  is the momentum operator, and  $\hbar$  is Planck's constant.

## References

- [1] Lie Groups, Lie Algebras, and Representations An Elementary Introduction, Brian C.Hall
- [2] Groups and their representations, Serge Richard