

V.2 Equation of structure

Recall that a connection ∇ is a map

$$\nabla: \mathfrak{X}(M) \times \mathfrak{X}(M) \mapsto \mathfrak{X}(M)$$

$$X \quad Y \quad \mapsto \nabla_X Y$$

which is bilinear and satisfies

$$1) \nabla_{fX} Y = f \nabla_X Y$$

$$2) \nabla_X (fY) = (Xf)Y + f \nabla_X Y$$

∇ is torsion free if $\nabla_X Y - \nabla_Y X - [X, Y] (=: T(X, Y)) = 0$ and

∇ is compatible with the metric ^{for (M, ϕ)} if

$$Z \langle X, Y \rangle = \langle \nabla_Z X, Y \rangle + \langle X, \nabla_Z Y \rangle$$

making the parallel transport of 2 orthogonal vectors still orthogonal

Let U be an open subset of M and

let $\{F_j\}_{j=1}^n$ be a C^∞ -field of frames on U $\{F_j, p\}$ is a basis of $T_p(M) \forall p \in U$;
not necessarily orthonormal nor generated by a chart

e.g. the coordinate frames given by a chart (U, ϕ)

Let $\{\theta^j\}_{j=1}^n$ be a dual coframe, it means $\{\theta^j\}$ is a C^∞ -field of frames on $T^*(M)$

and $\{\theta_p^j\}$ is a basis of $T_p^*(M)$ with $\theta_p^j(F_{k,p}) = \delta_{jk}$ ^{Cronecker delta}

Recall that ∇ is uniquely determined by $\{\Gamma_{ij}^k\}$ defined by

$$\nabla_{F_i} F_j = \sum_k \Gamma_{ij}^k F_k$$

Def. $\theta_j^k := \sum_l \Gamma_{ij}^k \theta^l \in \mathcal{J}^1(M)$ ^{one form}

$\{\theta_j^k\}$ are called CONNECTION FORMS. Clearly

$$\Rightarrow \theta_j^k(F_i) = \Gamma_{ij}^k, \text{ and } \cdot$$

if $T(M) \ni X = \sum_l b^l F_l$ then

$$\nabla_X F_j = \nabla_{\sum_l b^l F_l} F_j \stackrel{\text{linear and 1)}}{=} \sum_l b^l \nabla_{F_l} F_j \stackrel{\text{linearity of 1 forms}}{=} \sum_l b^l \sum_k \Gamma_{lj}^k F_k$$

$$\stackrel{\text{Def of } \theta}{=} \sum_k \sum_l b^l \theta_j^k(F_l) F_k$$

Thus, $\theta_j^k(X)$ are the components of $\nabla_X F_j$ with respect to $\{F_k\}$.

For a R_0 manifold (M, ϕ) and for the Levi Civita connection ∇ ,

the n^2 connection form are not indep because of the relations \otimes .

Thm. (Structure Thm of Cartan) [GN p. 133]

Let (R, ϕ) be a Riemannian manifold, ∇ the Levi Civita connection, $U, \{E_i\}, \{\theta^j\}$ above.

Then the connection forms $\{\theta_j^k\}$ are the unique solution of the equations:

1) $d\theta^i = \sum_j \theta^j \wedge \theta_i^j$ wedge product equality between 2-forms

2) $dg_{ij} = \sum_k (g_{kj} \theta_i^k + g_{ki} \theta_j^k)$ equality between 1-forms

$\hookrightarrow \in C^\infty(M)$
 \hookrightarrow one-forms

Remark: If $\{F_j\}$ is an orthonormal basis,

$g_{ij} := \phi(F_i, F_j) = \delta_{ij}$ and 2) becomes

2) $0 = \theta_j^i + \theta_i^j$

Similarly, one can introduce the CURVATURE FORM for $X, Y \in \mathfrak{X}(M)$:

$\Omega_k^l(X, Y) := \theta^l(R(X, Y)F_k) \in C^\infty(M) \Rightarrow \Omega_k^l \in J^2(U) \subset J^2(M)$

which gives $\downarrow \in \mathfrak{X}(M)^* \in \mathfrak{X}(M) \Rightarrow \uparrow$

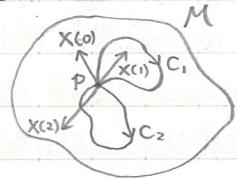
$R(X, Y)F_k = \sum_j \Omega_k^j(X, Y) F_j$

Thus $\Omega_k^l(X, Y)$ are components of $R(X, Y)F_k$ on the basis $\{F_j\}$

Remark: $\Omega_k^l \in J^2(U) \subset J^2(M)$ and one has

Thm. (Structure Thm of Cartan) [GN p. 135; Bo p. 391]

$\Omega_i^j = d\theta_j^i - \sum_k \theta_i^k \wedge \theta_j^k$ equality between 2-forms



V.3 Holonomy for a connected Riemannian manifold

⚠ Exists in a more general context of vector bundles or principal bundles.

Let $c: [0, 1] \ni t \mapsto c(t) \in M$ a smooth curve on (M, ϕ)

with $c(0) = c(1) = p$.

Let $X_p \in T_p(M)$ and let $X(t)$ be the parallel transport of X_p along c with $X(0) = X_p$. Let

$P_c: T_p(M) \ni X_p = X_0 \mapsto X_1 \in T_p(M)$, and clearly

$P_{c_2 \circ c_1} = P_{c_2} P_{c_1}$; $P_{c^{-1}} = P_c^{-1}$ leading to the fact that it composes a group.

\uparrow composition of paths \uparrow backward

\uparrow invertible matrices

In addition $P_c \in GL(T_p(M))$ because the parallel transport is a solution of a homogenous equation. \Rightarrow linear in the initial condition

In fact $P_c \in O(T_p(M))$ orthogonal matrices on $T_p(M)$

because the parallel transport preserves norms and scalar products.

Remark: Instead of smooth curve, we can consider C^1 -piecewise curves.

We have obtained that

$\{P_c\}_* \subset O(T_p(M))$ is a group e is the zero path

called the HOLONOMY GROUP at p and denoted $Hol(p)$.

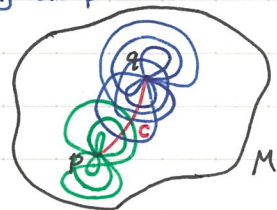
$*$:= "any C^1 -piecewise curve starting and ending at p "

If p and q are 2 points on M then

$Hol(p)$ is isomorphic to $Hol(q)$ since

$$Hol(p) = P_c^{-1} Hol(q) P_c$$

for some fixed path c between q and p .



Def. We set $Hol(M) = Hol(p) \subset O(n)$ for a fixed $p \in M$, and call it the HOLONOMY GROUP of M .

We also set $Hol^\circ(M)$ constructed only with C^1 -piecewise path which can be deformed to the zero path.

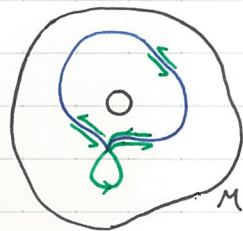
Remarks:

1) These groups are representations of the group of paths on M .

2) $Hol^\circ(M)$ is a normal subgroup of $Hol(M)$.

Lemma

M is orientable iff $Hol(M) \subset SO(n)$ determinant 1 and never -1



(Thm (deep notation))
 $Hol^\circ(M)$ is compact (it is a closed set in $O(n)$)

Remark [see App. 12]

There is a link between holonomy and the curvature tensor $R(X, Y)$

