

Homework 6

Exercise 1 1. Find some $\mathcal{A} \in M_2(\mathbb{R})$ such that $\mathcal{A}^2 = -\mathbf{1}_2$.

2. Determine all $\mathcal{A} \in M_2(\mathbb{R})$ such that $\mathcal{A}^2 = \mathcal{O}$.

Exercise 2 Let a, b be real numbers and let

$$\mathcal{A} = \begin{pmatrix} 1 & a \\ 0 & 1 \end{pmatrix} \quad \text{and} \quad \mathcal{B} = \begin{pmatrix} 1 & b \\ 0 & 1 \end{pmatrix}.$$

What is $\mathcal{A}\mathcal{B}$? Compute \mathcal{A}^2 and \mathcal{A}^3 . What is \mathcal{A}^m for an arbitrary integer m , and how to prove it?

Exercise 3 One says that a matrix $\mathcal{A} \in M_n(\mathbb{R})$ is orthogonal if ${}^t\mathcal{A} = \mathcal{A}^{-1}$, or equivalently if ${}^t\mathcal{A}\mathcal{A} = \mathbf{1}_n$. Show that if $\mathcal{A} \in M_n(\mathbb{R})$ is an orthogonal matrix, then

1. $\|\mathcal{A}X\| = \|X\|$ for any $X \in \mathbb{R}^n$,
2. $(\mathcal{A}X) \cdot (\mathcal{A}Y) = X \cdot Y$ for any $X, Y \in \mathbb{R}^n$.

In other words, orthogonal matrices preserve lengths and angles between vectors of \mathbb{R}^n .

Exercise 4 A special type of 2×2 matrices represents rotations in the plane. For arbitrary $\theta \in \mathbb{R}$, consider the matrix

$$R(\theta) = \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix}.$$

1. For ${}^tX = (1, 2)$, what are its coordinates after a rotation of $\pi/4$?
2. For ${}^tY = (-1, 3)$, what are its coordinates after a rotation of $\pi/2$?
3. Show that for arbitrary θ_1, θ_2 one has $R(\theta_1)R(\theta_2) = R(\theta_2)R(\theta_1)$,
4. Show that for arbitrary θ_1, θ_2 one has $R(\theta_1)R(\theta_2) = R(\theta_1 + \theta_2)$,
5. Show that for any θ , the matrix $R(\theta)$ has an inverse and write down this inverse.

Exercise 5 Let

$$\mathcal{A} = \begin{pmatrix} 1 & 0 & 2 & 0 \\ 0 & 3 & 0 & 4 \\ 5 & 0 & 6 & 0 \\ 0 & 7 & 0 & 8 \end{pmatrix}$$

and let \mathcal{U} be one of the matrices shown below. Compute $\mathcal{U}\mathcal{A}$.

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|---|---|---|
| a) $\mathcal{U} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$ | b) $\mathcal{U} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$ | c) $\mathcal{U} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$ |
| d) $\mathcal{U} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$ | e) $\mathcal{U} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}$ | f) $\mathcal{U} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$ |

Exercise 6 Do the same exercise with the following matrices \mathcal{U} and \mathcal{A} as above:

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|---|---|---|--|
| a) $\mathcal{U} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$ | b) $\mathcal{U} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$ | c) $\mathcal{U} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 5 & 0 & 1 \end{pmatrix}$ | d) $\mathcal{U} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -2 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$ |
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