

## §2 KdV Equation and Wronskian

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### 2.0 Introduction ( $\rightarrow$ Slide)

### 2.1 Definition & Properties

Def 2.1 (KdV eq.)  $u = u(t, x)$ : defined on (1+1)-dim space-time

$$u_t + u_{xxx} + 6u u_x = 0 \quad \dots \textcircled{1}$$

$\uparrow$  partial derivatives  $\uparrow$  non-linear term (hard to solve)

Rmk 2.2 Three coefficients are arbitrary

i.e.  $\textcircled{1} \iff \tilde{u}_{\tilde{t}} + A u_{xxx} + B u u_x = 0$

$$\tilde{u} = \frac{6A}{B} u$$
$$\tilde{t} = \frac{1}{A} t$$

Def 2.3 For  $D(t, x)$ ,  $F(t, x)$ ,  $F(t, x \rightarrow \pm\infty) = 0$ ,

$D_t + F_x = 0$  is called conservation law.

$D$ : conserved density,  $F$ : flux

Prop 2.4  $I := \int_{-\infty}^{\infty} D dx$  is conserved (i.e.  $\frac{dI}{dt} = 0$ )

$$\textcircled{\ominus} \frac{dI}{dt} = \int_{-\infty}^{\infty} D_t dx = - \int_{-\infty}^{\infty} F_x dx = -F \Big|_{x=-\infty}^{x=+\infty} = 0 \quad \square$$

Thm 2.5 KdV eq has  $\infty$  conserved densities

c.g.  $D_1 = u$ ,  $D_2 = u^2$ ,  $D_3 = u^3 - \frac{1}{2} u_x^2$ , ...

$\textcircled{\ominus}$  See, e.g. [D], [MJD]

## 2.2 Hirota trf. & Wronskian solution ( $\tau$ -fcn) ⑥

Def 2.6 (Hirota trf.)  $u = 2 \partial_x^2 \log \tau(t, x) \dots$  ②

Prop 2.7 KdV eq. is transformed by ② to

$$\tau \tau_{xt} - \tau_x \tau_t + 3 \tau_{xx}^2 - 4 \tau_x \tau_{xxx} + \tau \tau_{xxxx} = 0 \dots$$
 ③

(Hirota's) bilinear eq.

☺ **Quiz 1: Prove this.** ( ①  $\xrightarrow{②}$   $(\dots)_x = 0 \xrightarrow{x\text{-integ. \& } C=0}$  ③ )

Def 2.8 (Wronskian)

$$\text{Wr}(f_1, \dots, f_n) := \begin{vmatrix} f_1 & f_2 & \dots & f_n \\ f_1' & f_2' & & f_n' \\ \vdots & \vdots & & \vdots \\ f_1^{(n-1)} & f_2^{(n-1)} & & f_n^{(n-1)} \end{vmatrix} \quad \begin{array}{l} f_i : C^\infty \text{ fcn of } x \\ f_i^{(k)} : k\text{-th } x\text{-derivative of } f_i \end{array}$$

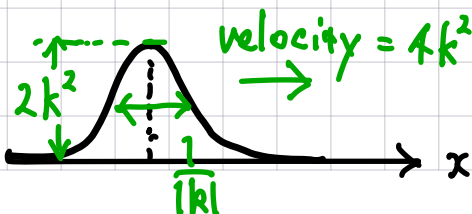
Thm 2.9 General solutions of ③ are the following Wronskians:

$$\tau = \text{Wr}(f_1, \dots, f_N) \quad f_{i,t} = 4 f_{i,xxx}$$

N-soliton solutions are given by the choice:

$$f_i = e^{\theta_i} + a_i e^{-\theta_i}, \quad \theta_i := k_i x - 4k_i^3 t \quad (a_i > 0)$$

Ex 1-soliton solution:  $u = 2 \partial_x^2 \log (e^{kx - 4k^3 t} + a e^{-kx + 4k^3 t})$



$$= 2k^2 \text{cosh}^{-2} (kx - 4k^3 t - \frac{1}{2} \log a)$$

# Asymptotic behavior of the N-soliton solution

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For simplicity, set  $a_i \equiv 1$  &  $0 < k_1 < k_2 < \dots < k_N$

Consider the comoving frame where  $X_I = x - 4k_I^2 t$  is finite.

$$\frac{\theta_i}{k_i} = x - 4k_i^2 t = \underbrace{x - 4k_I^2 t}_{\text{finite}} - 4(k_i^2 - k_I^2)t$$

$$f_i = e^{\theta_i} + e^{-\theta_i} \xrightarrow{t \rightarrow +\infty} \begin{cases} e^{\theta_i} & i < I \\ e^{\theta_I} + e^{-\theta_I} & i = I \\ e^{-\theta_i} & i > I \end{cases}$$

( $t \rightarrow -\infty$  case)  
is similar

$$\tau \xrightarrow{t \rightarrow \infty} \begin{vmatrix} e^{\theta_1} & \dots & e^{\theta_I} + e^{-\theta_I} & \dots & e^{-\theta_N} \\ k_1 e^{\theta_1} & \dots & k_I e^{\theta_I} + (-k_I) e^{-\theta_I} & \dots & (-k_N) e^{-\theta_N} \\ \vdots & & \vdots & & \vdots \\ k_1^{N-1} e^{\theta_1} & \dots & k_I^{N-1} e^{\theta_I} + (-k_I)^{N-1} e^{-\theta_I} & \dots & (-k_N)^{N-1} e^{-\theta_N} \\ 1 & \dots & e^{\theta_I} + e^{-\theta_I} & \dots & 1 \\ k_1 & & k_I e^{\theta_I} + (-k_I) e^{-\theta_I} & & (-k_N) \\ \vdots & & \vdots & & \vdots \\ k_1^{N-1} & \dots & k_I^{N-1} e^{\theta_I} + (-k_I)^{N-1} e^{-\theta_I} & & (-k_N)^{N-1} \end{vmatrix}$$

$\Delta(a_1, \dots, a_N)$   
van der Monde det  
"  
 $\prod_{i < j} (a_i - a_j)$

$e^{\text{linear}}$   
not contribute  $u$

$$= \underbrace{\Delta(k_1, \dots, k_I, (-k_{I+1}), \dots, (-k_N))}_{\Delta_{I,1}} e^{\theta_I} + \underbrace{\Delta(k_1, \dots, k_{I-1}, (-k_I), \dots, (-k_N))}_{\Delta_{I,2}} e^{-\theta_I}$$

$$u = \partial_x^2 \log \tau = 2k_I^2 \cosh^{-2} \left( k_I x - 4k_I^3 t + \frac{1}{2} \log \frac{\Delta_{I,1}}{\Delta_{I,2}} \right)$$

(I-th) 1-soliton with the position shift (phase shift)

## 2.3 Lax form & KdV hierarchy

[MJD][D]

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### Def 2.10 (Lax form)

Consider the linear system:

$$\begin{cases} P\psi = 0 \\ \partial_t \psi = B\psi \end{cases} \quad \begin{matrix} \text{Lax} \\ \text{pair} \end{matrix} \quad \begin{cases} P := \partial_x^2 + u \\ B := -4\partial_x^3 - 6u\partial_x - 3u_x \end{cases}$$

The compatible condition  $[\partial_t - B, P] = 0 \dots \textcircled{4}$

give rise to the KdV eq.

( $\nearrow u_t = [B, P]$ )  
evolution eq. or flow eq.

☹ Quiz 2 Show this  $\uparrow$

(a little bit difficult)

$\textcircled{4}$  means  $(\partial_t - B)(P\psi) - P(\partial_t - B)\psi = 0$   
(for  $\forall \psi$ )

Thm 2.11 There exist  $\infty$  flow eqs.

$$\frac{\partial u}{\partial t_{2n+1}} = [B_{2n+1}, P]$$

now  $u = u(x, t_3, t_5, t_7, \dots)$

such that  $\partial_{t_{2m+1}} \partial_{t_{2n+1}} u - \partial_{t_{2n+1}} \partial_{t_{2m+1}} u = 0$  ( $\forall m, n$ )

(commuting flows)

This is called the KdV hierarchy

$$u_{t_3} = [B_3, P] \Rightarrow \text{(3rd) KdV eq} \quad (t_3 \equiv t, B_3 \equiv B) \text{ in } \textcircled{4}$$

$$u_{t_5} = [B_5, P] \Rightarrow \text{(5th) " (exist)}$$

$$u_{t_7} = [B_7, P] \Rightarrow \text{(7th) " (" )}$$

$\vdots$

(" )

infinite commuting flows

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↓

$u = u(x, t_3, t_5, t_7, \dots)$  : defined on  $\infty$ -dim "space-time"

- $u$  has common conserved density:  $\frac{\partial}{\partial t_{2n+1}} D_k = 0$   
conserved density in Thm 2.5
- KdV hierarchy eqs. are transformed to bilinear eqs.

3rd KdV  $\longrightarrow$  bilinear eq. ③

5th KdV  $\longrightarrow$  another bilinear eq.

$\vdots$   $u = 2 \partial_x^2 \log \tau$   $\vdots$

- $\tau(x, t_3, t_5, t_7, \dots)$  has common Wronskian solutions

$$\tau = \text{Wr}(f_1, \dots, f_N)$$

$$f_k = f_k(x, t_3, t_5, t_7, \dots)$$

$$\partial_{t_{2n+1}} f_k = 4 \partial_x^{2n+1} f_k$$